

Average of Synthetic Exact Filters

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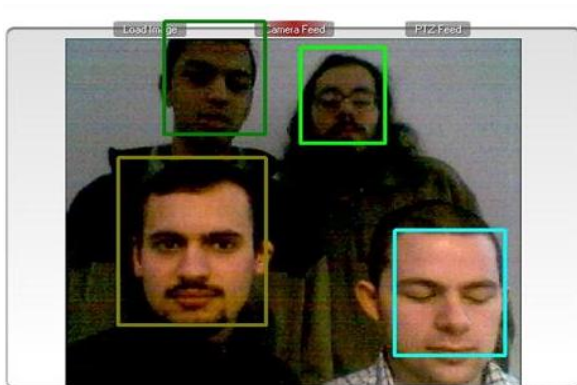
Outline

- 1 Introduction
 - Face Recognition
 - Eye Localization
- 2 Review
- 3 Constructing Filters
- 4 Experimentation
 - Experiment 1: Restrictions
 - Experiment 2: No Restrictions
- 5 My Experiment

First step: Face Registration

How?

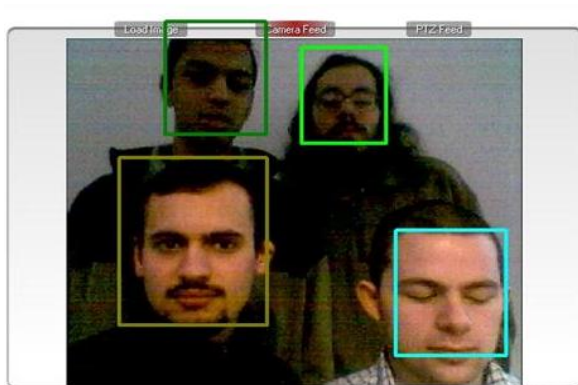
Find the eyes



First step: Face Registration

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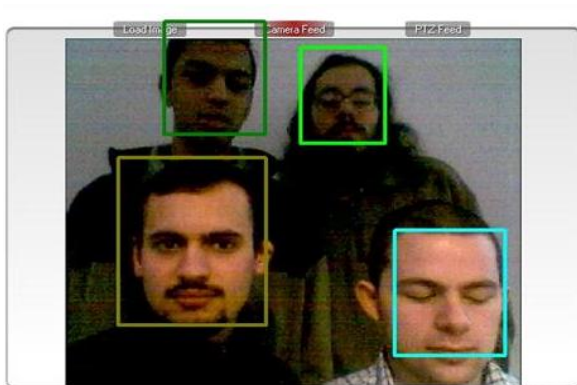
Find the eyes



First step: Face Registration

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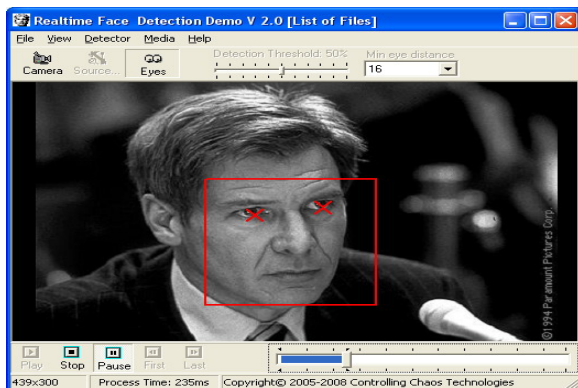
Find the eyes



Eye Localization

Goal:

Return pixel coordinates of eye center to within some tolerance



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Problems

Two types of problems:

- 1 Prior Knowledge (e.g. location of face, known region of eye)
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Convolution vs. Correlation

Convolution:

$$(f * g)[n] = \sum_{m=-\infty}^{\infty} f[m] \cdot g[n - m]$$

Correlation:

$$(f \otimes g)[n] = \sum_{m=-\infty}^{\infty} f^*[m] \cdot g[n + m]$$

Convolution/Correlation Theorem

Convolution Theorem:

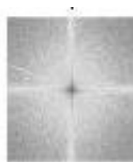
$$\mathcal{F}(f * g) = \mathcal{F}(f) \cdot \mathcal{F}(g)$$

"Correlation" Theorem:

$$\mathcal{F}(f \otimes g) = [\mathcal{F}(f)]^* \cdot \mathcal{F}(g)$$

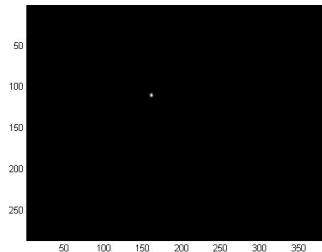
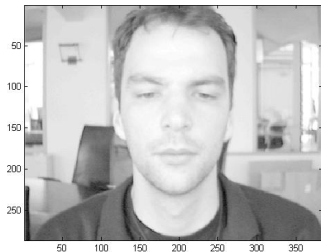
Filtering Process

correlation filter



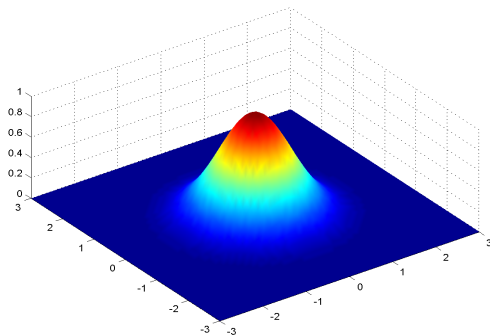
test image

How to Construct Filters



Desired Output: Gaussian

$$g_i(x, y) = e^{\frac{-(x-x_i)^2 - (y-y_i)^2}{\sigma^2}}$$



Proof

Let $f_i(x, y)$ be an image in training set and let $g_i(x, y)$ be desired output. We want filter $h_i(x, y)$ such that

$$f_i(x, y) * h_i(x, y) = g_i(x, y)$$

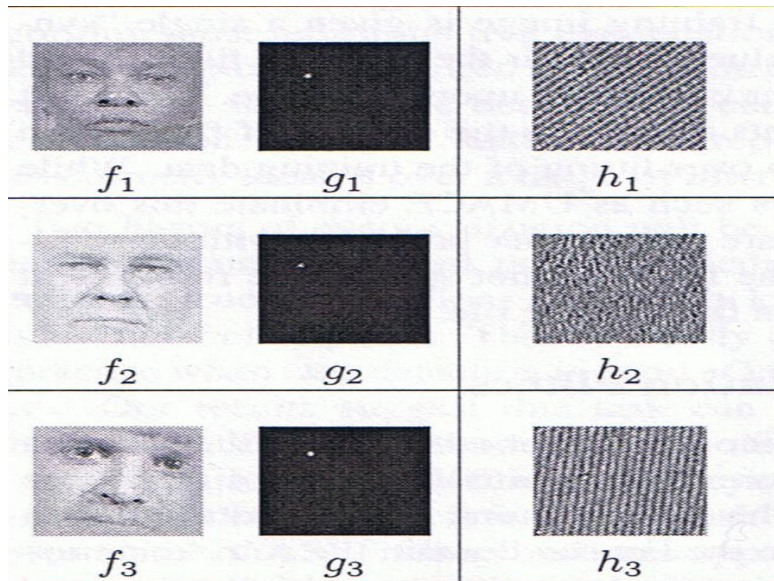
Taking Fourier Transform of both sides and applying Convolution Theorem

$$F_i(x, y) \cdot H_i(x, y) = G_i(x, y)$$

or

$$H_i(x, y) = \frac{G_i(x, y)}{F_i(x, y)}$$

Exact Filters



Averaging

Now that we have h_i let us calculate their average

$$h = \sum_{i=1}^N h_i(x, y) \quad (1)$$

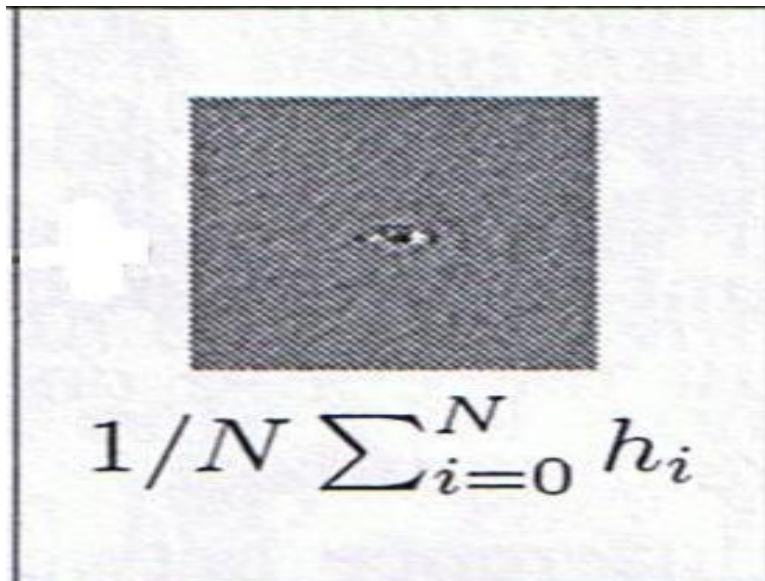
Now that we have filter we can apply it.

Averaging?

But wait...why average?

Averaging emphasizes common features and suppresses those specific to an image.

Final Filter



Experimentation

- Left Eye
- Feret Database
- 1024 images for training set
- 1699 images for testing set
- Similarity transforms: rotations($\pm\frac{\pi}{6}$), scaling(1.0 ± 0.1), translations(± 4.0)
- Error $D = \frac{\|P_l - M_l\|}{\|M_l - M_r\|}$
- $D < .10$ is a success

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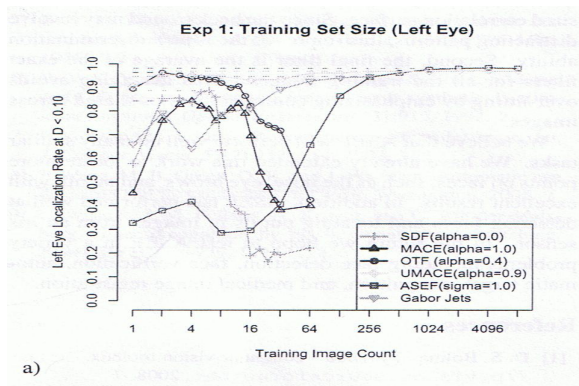
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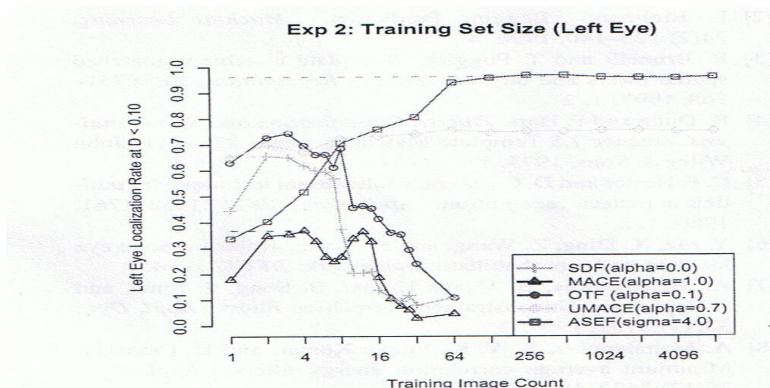
Experiment with Restriction

Search in region of expected location.



Experiment without Restrictions

Search entire image



My Experiment

- Used Convolution not Correlation
- No Restrictions
- Normalization: $\log(v + 1)$
- Used 1000 images from BioID database



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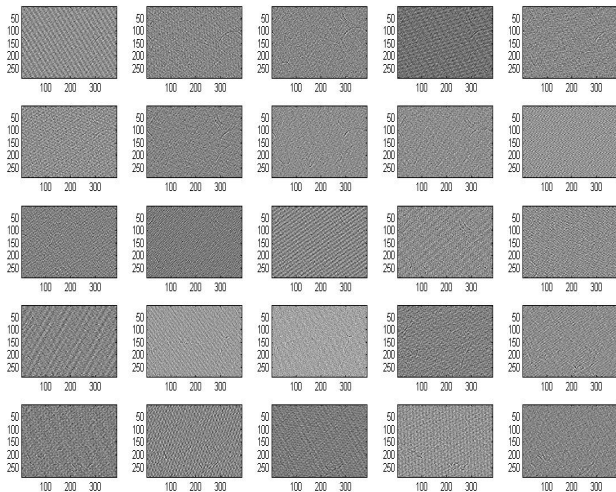


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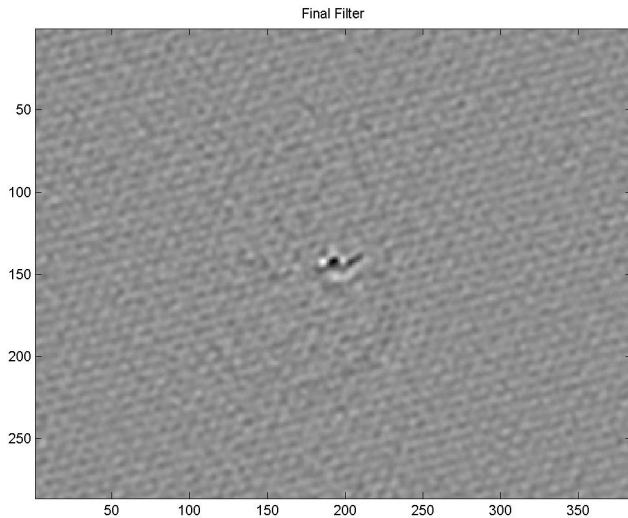
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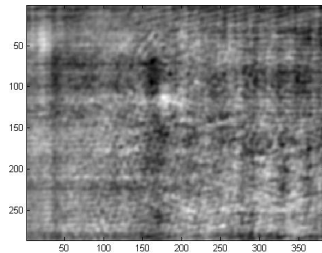
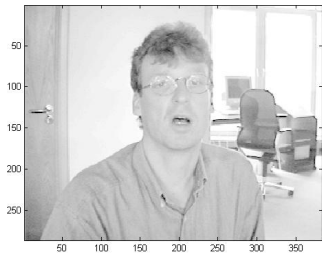
My Exact Filters



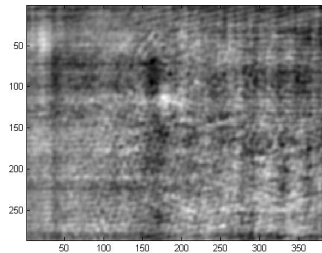
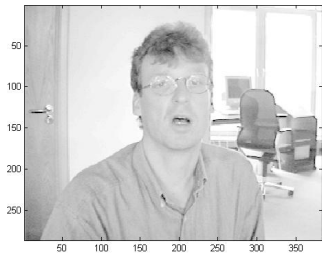
My Final Filter



Let's Try It!

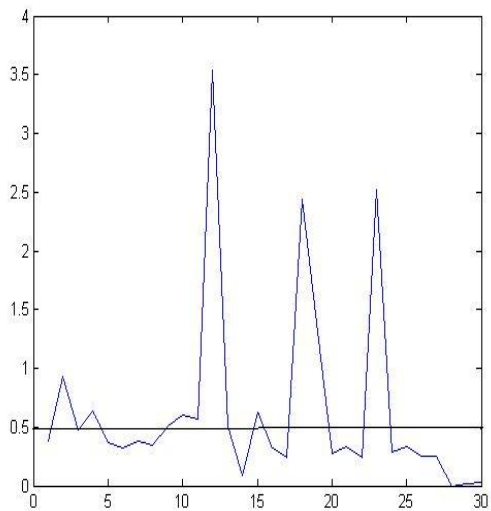


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How Well Did It Work?

- $P_l = (177, 113)$
- $M_r = (177, 97)$
- $M_l = (219, 95)$
- $D = \frac{\|P_l - M_l\|}{\|M_r - M_l\|} = .3805$



Reference

Title:

Average of Synthetic Exact Filters

Authors:

David S. Bolme

Bruce A. Draper

J. Ross Beveridge